

0026-7683(94)EOO3S-T

# BENDING SOLUTION OF HIGH-ORDER REFINED SHEAR DEFORMATION THEORY FOR RECTANGULAR COMPOSITE PLATES

LIU PING†, ZHANG YONGWEI‡ and ZHANG KAIDA† tDepartment of Aircraft, Northwestern Polytechnical University, Xi'an, 710072, People's Republic of China :j:Basic Research Division, Institute of Mechanics, Chinese Academy of Sciences, Beijing, 100080, People's Republic of China

*(Received* 8 *July* 1993; *in revisedfarm* 28 *February 1994)*

Abstract-A new high-order refined shear deformation theory based on Reissner's mixed variational principle in conjunction with the state-space concept is used to determine the deflections and stresses for rectangular cross-ply composite plates. A zig-zag shaped function and Legendre polynomials are introduced to approximate the in-plane displacement distributions across the plate thickness. Numerical results are presented with different edge conditions, aspect ratios, lamination schemes and loadings. A comparison with the exact solutions obtained by Pagano and the results by Khdeir indicates that the present theory accurately estimates the in-plane responses.

#### I. INTRODUCTION

Three-dimensional elasticity solutions for the bending ofsimply supported thick orthotropic rectangular plates and laminates were obtained by Srinivas and Rao (1970), Srinivas *et al.* (1970), Hussainy and Srinivas (1975) and Pagano (1970). The Navier solution of simply supported rectangular plates was developed by Whitney and Leissa (1969) for classical laminate theory, Whitney and Pagano (1970), Bert and Chen (1978) and Reddy and Chao (1981) for the first-order shear deformation (i.e. the Reissner-Mindlin plate) theory, and by Reddy (1984a,b) and Reddy and Phan (1985) for refined shear deformation theories. The Levy type solutions were developed by Reddy *et al.* (1987) for symmetric laminates with different combinations of free, clamped and simply supported boundary conditions by using the first-order shear deformation theory. Khdeir *et al.* (1987) later extended Reddy's work by using refined shear deformation theory.

Murakami (1986) proposed an improved in-plane response theory based on Reissner's (1984) mixed variational principle and applied it to cylindrical bending problem of laminated plates, the improvement was achieved by including a zig-zag shaped function to approximate the in-plane displacements across the thickness. However, this theory cannot exactly describe the deformation of the anti-symmetric and irregular laminated plates.

Based upon Murakami's theory, Legendre polynomials are introduced in the displacement field and the transverse normal strain is also included in present theory so that the in-plane displacement distribution for arbitrary laminated configurations can be determined exactly. The advantage of using Reissner's mixed variation principle is that it automatically yields the appropriate shear correction factors for the transverse shear constitutive equations. Other attractive features of the present theory are:  $(1)$  the continuity condition of transverse shear stresses at the interfaces is satisfied; (2) the effects of the transverse shear and transverse normal strains are accounted; (3) the number of equations remains unchanged as the number of layers increases.

The accuracy of the present theory is examined by applying it to bending problem of rectangular laminates with two opposite edges simply supported and the remaining edges subject to a combination of free, simply supported and clamped boundary conditions. Different aspect ratios, lamination schemes and loadings are considered. The state-space concept is used to solve the ordinary differential equations.

#### Liu Ping et al.

### 2. GOVERNING EQUATIONS

Consider an N-layer laminated composite plate, shown in Fig. 1. The following notation,  $(y^{(k)}, k = 1, 2...N$ , will designate quantities associated with the kth layer. The thickness of each layer is  $n^{(k)}h$ . Unless otherwise specified, the usual Cartesian indicial notation is employed where Latin and Greek indices range from 1 to 3 and 1 to 2, respectively. Repeated indices imply the summation convection and  $( )$ , denotes partial differentiation with respect to  $x_i$ .

Constitutive equations for orthotropic layers (Murakami, 1986):

$$
\begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{12} \end{bmatrix}^{(k)} = \begin{bmatrix} \bar{c}_{11} & \bar{c}_{12} & 0 \\ \bar{c}_{12} & \bar{c}_{22} & 0 \\ 0 & 0 & c_{66} \end{bmatrix}^{(k)} \begin{bmatrix} e_{11} \\ e_{22} \\ 2e_{12} \end{bmatrix}^{(k)} + \begin{bmatrix} \frac{c_{13}}{c_{33}} \\ \frac{c_{23}}{c_{33}} \\ 0 \end{bmatrix}^{(k)} \sigma_{33}^{(k)} \tag{1a}
$$

$$
\begin{bmatrix} e_{33} \ 2e_{23} \ 2e_{31} \end{bmatrix}^{(k)} = - \begin{bmatrix} \frac{c_{13}}{c_{33}} & \frac{c_{23}}{c_{33}} & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}^{(k)} \begin{bmatrix} e_{11} \ e_{22} \ 2e_{12} \end{bmatrix}^{(k)} + \begin{bmatrix} \frac{1}{c_{33}} & 0 & 0 \\ 0 & \frac{1}{c_{44}} & 0 \\ 0 & 0 & \frac{1}{c_{55}} \end{bmatrix}^{(k)} = - \begin{bmatrix} \sigma_{33} \ \sigma_{23} \ \sigma_{31} \end{bmatrix}^{(k)}; \quad (1b)
$$

strain-displacement relations

$$
e_{ij}^{(k)} = \frac{1}{2} (u_{i,j}^{(k)} + u_{j,i}^{(k)}); \qquad (2)
$$



Fig. 1. Plate geometry coordinate system and trial in-plane displacements.

interface continuity conditions

$$
u_i^{(k)} = u_i^{(k+1)}
$$
 and  $\sigma_{3i}^{(k)} = \sigma_{3i}^{(k+1)}$   $k = 1, 2...N-1$  ; (3)

upper and lower surface stress conditions

$$
\sigma_{3i}^{(1)} = T_i^+ \quad \text{on} \quad x_3 = \frac{h}{2} \tag{4a}
$$

$$
\sigma_{3i}^{(N)} = T_i^- \quad \text{on} \quad x_3 = -\frac{h}{2}.\tag{4b}
$$

Reissner's mixed variational principle was applied to N-layer composite plate whose middle surface occupies a domain *D* in the  $x_1$ ,  $x_2$ -plane:

$$
\iiint_{D} \left[ \sum_{k} \int_{A^{(k)}} \{ \delta e_{ij}^{(k)} \sigma_{ij}^{(k)} + [u_{\alpha,3}^{(k)} + u_{3,\alpha}^{(k)} - 2e_{3\alpha}^{(k)} (\ldots)] \delta \tau_{3\alpha}^{(k)} + [u_{3,3}^{(k)} - e_{3\alpha}^{(k)} (\ldots)] \delta \tau_{3\alpha}^{(k)} \} dx_{3} \right] dx_{1} dx_{2}
$$
\n
$$
= \int_{\partial D_{T}} \left[ \sum_{k} \int_{A^{(k)}} \delta u_{i}^{(k)v} T_{i}^{(k)} dx_{3} \right] ds + \iint_{D} \left[ \delta u_{i}^{(1)} \left( x_{1}, x_{2}, \frac{h}{2} \right) T_{i}^{+} - \delta u_{i}^{(N)} \left( x_{1}, x_{2}, -\frac{h}{2} \right) T_{i}^{-} \right] dx_{1} dx_{2}, \quad (5)
$$

where  $\partial D_T$  denotes the boundary of D with outward normal  $v_\alpha$  on which tractions  $T_i$  are specified and  $A^{(k)}$  represents the x<sub>3</sub>-domain occupied by the *k*th layer. Also  $\tau_{3i}^{(k)}$  denote the approximate transverse stresses and  $e_{3i}^{(k)}$ ... implies the appropriate right-hand side of eqn (lb).

The high-order laminated plate theory, which takes into account the effect of transverse shear strains, is obtained by including the Legendre polynomials of order  $n = 1, 2, 3$ , with respect to the  $x_3$ -coordinate to a zig-zag in-plane displacement variation of amplitude  $S_i(x_1,$  $(x_2)$  across the plate thickness.

The appropriate trial functions used in connection with Reissner's mixed variational principle eqn (5) are taken to be:

(a) trial displacement field (see Fig. 1)

$$
u_i^{(k)}(x_1, x_2, x_3) = U_i(x_1, x_2) + \frac{h}{2} \Psi_i(x_1, x_2) P_1(\zeta) + S_i(x_1, x_2) (-1)^k \frac{2}{n^{(k)} h} x_3^{(k)} + \left(\frac{h}{2}\right)^2 \zeta_i(x_1, x_2) P_2(\zeta) + \left(\frac{h}{2}\right)^3 \Phi_i(x_1, x_2) P_3(\zeta), \quad (6)
$$

where  $\zeta \equiv 2x_3/h$  and  $P_n(\zeta)$  are the Legendre polynomials of order n and  $\Phi_3 \equiv 0$ ,  $x_3^{(k)}$  is a local x<sub>3</sub>-coordinate system with its origin at the center  $x_{30}^{(k)}$  of the *k*th layer, i.e.

$$
x_3^{(k)} \equiv x_3 - x_{30}^{(k)}; \tag{7}
$$

(b) trial transverse and normal stresses

$$
\tau_{3a}^{(k)}(x_1, x_2, x_3) = Q_{\alpha}^{(k)}(x_1, x_2)F_1(z) + R_{\alpha}^{(k)}(x_1, x_2)F_2(z)
$$
  
+ 
$$
J_{\alpha}^{(k)}(x_1, x_2)F_3(z) + [T_{\alpha}^{(k-1)}(x_1, x_2) + T_{\alpha}^{(k)}(x_1, x_2)]F_4(z)
$$
  
+ 
$$
[T_{\alpha}^{(k-1)}(x_1, x_2) - T_{\alpha}^{(k)}(x_1, x_2)]F_5(z)
$$
(8a)

Liu Ping *et at,*

$$
\tau_{33}^{(k)}(x_1, x_2, x_3) = Q_3^{(k)}(x_1, x_2)F_1(z) + R_3^{(k)}(x_1, x_2)F_6(z)
$$
  
+  $J_3^{(k)}(x_1, x_2)F_3(z) + I_3^{(k)}(x_1, x_2)F_7(z)$   
+  $[T_3^{(k-1)}(x_1, x_2) + T_3^{(k)}(x_1, x_2)]F_4(z)$   
+  $[T_3^{(k-1)}(x_1, x_2) - T_3^{(k)}(x_1, x_2)]F_8(z),$  (8b)

where

$$
F_1(z) = \frac{5}{n^{(k)}h} \left( 21z^4 - \frac{15}{2}z^2 + \frac{9}{16} \right), \qquad F_2(z) = \frac{-30}{(n^k h)^2} (4z^3 - z)
$$
  
\n
$$
F_3(z) = \frac{-105}{(n^{(k)}h)^3} \left( 20z^4 - 6z^2 + \frac{1}{4} \right), \qquad F_4(z) = 35z^4 - \frac{15}{2}z^2 + \frac{3}{16}
$$
  
\n
$$
F_5(z) = 10z^3 - \frac{3}{2}z, \qquad F_6(z) = \frac{105}{(n^k h)^2} \left( 36z^5 - 14z^3 + \frac{5}{4}z \right)
$$
  
\n
$$
F_7(z) = \frac{-315}{(n^{(k)}h)^4} (112z^5 - 40z^3 + 3z), \qquad F_8(z) = 126z^5 - 35z^3 + \frac{15}{8}z \qquad (9)
$$

$$
z \equiv \frac{x_3^{(k)}}{n^{(k)}h} \quad -\frac{1}{2} \leqslant z \leqslant \frac{1}{2}.
$$

Also

$$
(\mathcal{Q}_{i}^{(k)}, R_{i}^{(k)}, J_{i}^{(k)}) \equiv \int_{A^{(k)}} (1, x_{3}^{(k)}, x_{3}^{(k)2}) \tau_{3i}^{(k)} dx_{3}
$$
 (10a)

$$
I_3^{(k)} \equiv \int_{A^{(k)}} x_3^{(k)3} \tau_{33}^{(k)} dx_3.
$$
 (10b)

In eqn (8),  $T_i^{(k-1)}$  and  $T^{(i)}$  are the values of  $\tau_{3i}^{(k)}$  at the top and bottom surfaces of the  $k$ th layer, respectively, from eqn  $(4)$ 

$$
T_i^{(0)} = T_i^+ \quad \text{and} \quad T_i^{(N)} = T_i^-.
$$
 (11)

The functions  $F_i(z)$ ,  $i = 1...8$  are obtained by first noting that eqn (6) yields cubic variations across the plate thickness of in-plane stresses. From the equilibrium equations (i.e.  $\sigma_{ii,j}^{(k)} = 0$ ), transverse stresses  $\tau_{3a}^{(k)}$  and  $\tau_{3a}^{(k)}$  may, as a result, be represented by polynomials of degree 4 and 5 in *z,* respectively. Their corresponding coefficients are then computed by using eqns (10a, b). This yields the functions  $F_i(z)$ .

Substituting eqns (6) and (8) into eqn (5), using Gauss' theorem and the orthogonality relationship of the Legendre polynomials, one obtains laminated plate equations: (a) equilibrium equations

$$
N_{\alpha i,\alpha} + T_i^+ - T_i^- = 0 \tag{12a}
$$

$$
M_{ai,a} - N_{3i} + \frac{h}{2}(T_i^+ + T_i^-) = 0 \tag{12b}
$$

$$
Z_{\alpha i,\alpha} - K_{3i} - [T_i^+ - (-1)^N T_i^-] = 0 \qquad (12c)
$$

$$
L_{\alpha i,\alpha} - 3M_{3i} + \frac{h^2}{4}(T_i^+ - T_i^-) = 0 \tag{12d}
$$

Bending solution of high-order refined shear deformation theory 2495

$$
P_{\beta\alpha,\beta} - \left(5L_{3\alpha} + \frac{h^2}{4}N_{3\alpha}\right) + \frac{h^3}{8}\left(T_{\alpha}^+ + T_{\alpha}^-\right) = 0,\tag{12e}
$$

$$
[N_{\alpha\beta}, M_{\alpha\beta}, Z_{\alpha\beta}, L_{\alpha\beta}, P_{\alpha\beta}] \equiv \sum_{k=1}^{N} \int_{A^{(k)}} \left[ 1, \frac{h}{2} P_1(\zeta), (-1)^k \frac{2x_3^{(k)}}{n^{(k)}h}, \left( \frac{h}{2} \right)^2 P_2(\zeta), \left( \frac{h}{2} \right)^3 P_3(\zeta) \right] \sigma_{\alpha\beta}^{(k)} dx_3 \quad (13a)
$$

$$
[N_{3i}, M_{3i}, K_{3i}, Z_{3i}, L_{3i}] \equiv \sum_{k=1}^{N} \int_{A^{(k)}} \left[ 1, \frac{h}{2} P_1(\zeta), (-1)^k \frac{2}{n^{(k)} h}, \left( -1 \right)^k \frac{2}{n^{(k)} h} x_3^{(k)}, \left( \frac{h}{2} \right)^2 P_2(\zeta) \right] \tau_{3i}^{(k)} dx_3 ; \quad (13b)
$$

(b) constitutive equations

(1) for transverse stresses

$$
Q_{\alpha}^{(k)} - \frac{8J_{\alpha}^{(k)}}{(n^{(k)}h)^2} + \frac{n^{(k)}h}{30} (T_{\alpha}^{(k-1)} + T_{\alpha}^{(k)})
$$
  
=  $\frac{2}{5} h n^{(k)} \tilde{c}_{\alpha}^{(k)} \left[ U_{3,\alpha} + \Psi_{\alpha} + S_{\alpha}(-1)^k \frac{2}{n^{(k)}h} + h n_0^{(k)} (\Psi_{3,\alpha} + 3\xi_{\alpha}) + \frac{h^2}{2} \left( 3n_0^{(k)2} - \frac{1}{4} \right) \xi_{3,\alpha} + \frac{3h^2}{2} \left( 5n_0^{(k)2} - \frac{1}{4} \right) \Phi_{\alpha} \right]$  (14a)

$$
\frac{1}{h} R_{\alpha}^{(k)} - \frac{n^{(k)} h}{40} (T_{\alpha}^{(k-1)} - T_{\alpha}^{(k)})
$$
\n
$$
= \frac{7h^2}{120} n^{(k)3} \tilde{c}_{\alpha}^{(k)} \left[ \Psi_{3,\alpha} + 3\xi_{\alpha} + S_{3,\alpha}(-1)^k \frac{2}{n^{(k)} h} + 3h n_0^{(k)} (\xi_{3,\alpha} + 5\Phi_{\alpha}) \right] \tag{14b}
$$

$$
Q_{\alpha}^{(k)} - \frac{14J_{\alpha}^{(k)}}{(n^{(k)}h)^2} + \frac{n^{(k)}h}{12}(T_{\alpha}^{(k-1)} + T_{\alpha}^{(k)}) = -\frac{3h^3}{40}n^{(k)3}\tilde{c}_{\alpha}^{(k)}(\xi_{3,\alpha} + 5\Phi_{\alpha})
$$
(14c)

$$
-\frac{1}{\tilde{c}_{\alpha}^{(k)}}\left[\frac{1}{12}\mathcal{Q}_{\alpha}^{(k)}-\frac{5J_{\alpha}^{(k)}}{3(n^{(k)}h)^{2}}+\frac{3R_{\alpha}^{(k)}}{7n^{(k)}h}\right]-\frac{1}{\tilde{c}_{\alpha}^{(k+1)}}\left[\frac{1}{12}\mathcal{Q}_{\alpha}^{(k+1)}-\frac{5J_{\alpha}^{(k+1)}}{3(n^{(k+1)}h)^{2}}-\frac{3R_{\alpha}^{(k+1)}}{7n^{(k+1)}h}\right]
$$

$$
=\frac{h}{126}\left[\frac{-n^{(k)}}{\tilde{c}_{\alpha}^{(k)}}T_{\alpha}^{(k-1)}+8\left(\frac{n^{(k)}}{\tilde{c}_{\alpha}^{(k)}}+\frac{n^{(k+1)}}{\tilde{c}_{\alpha}^{(k+1)}}\right)T_{\alpha}^{(k)}-\frac{n^{(k+1)}}{\tilde{c}_{\alpha}^{(k+1)}}T_{\alpha}^{(k+1)}\right];
$$
(14d)

(2) for normal stresses

$$
Q_{3}^{(k)} - \frac{8J_{3}^{(k)}}{(n^{(k)}h)^{2}} + \frac{n^{(k)}h}{30} (T_{3}^{(k-1)} + T_{3}^{(k)})
$$
  
=  $\frac{2h}{5}n^{(k)}c_{33}^{(k)} \left[ \Psi_{3} + S_{3}(-1)^{k} \frac{2}{n^{(k)}h} + 3hn_{0}^{(k)}\xi_{3} \right] + \frac{2h}{5}n^{(k)} \left[ \mathcal{O} + hn_{0}^{(k)}\tilde{\Psi} + \frac{h^{2}}{2} \left( 3n_{0}^{(k)2} - \frac{1}{4} \right) \tilde{\xi} + \frac{h^{3}}{2} \left( 5n_{0}^{(k)3} - \frac{3}{4}n_{0}^{(k)} \right) \tilde{\Phi} \right],$  (15a)

$$
\frac{1}{h}R_3^{(k)} - \frac{32I_3^{(k)}}{5n^{(k)}^2h^3} + \frac{n^{(k)}^2h}{140}(T_3^{(k-1)} - T_3^{(k)})
$$
\n
$$
= \frac{11}{350}h^2n^{(k)3}c_{33}^{(k)}\xi_3 + \frac{11}{1050}h^2n^{(k)3}\left[\tilde{\Psi} + (-1)^k\frac{2}{n^{(k)}h}\tilde{S} + 3hn_0^{(k)}\tilde{\xi} + \frac{3h^2}{2}\left(5n_0^{(k)2} - \frac{1}{4}\right)\tilde{\Phi}\right],
$$
\n(15b)

$$
Q_3^{(k)} - \frac{14J_3^{(k)}}{(n^{(k)}h)^2} + \frac{n^{(k)}h}{12}(T_3^{(k-1)} + T_3^{(k)}) = -\frac{3h^3}{40}n^{(k)3} \left[\tilde{\xi} + 5hn_0^{(k)}\tilde{\Phi}\right],\tag{15c}
$$

$$
\frac{1}{h}R_3^{(k)} - \frac{15I_3^{(k)}}{2n^{(k)}^2h^3} + \frac{n^{(k)}^2h}{96}(T_3^{(k-1)} - T_3^{(k)}) = -\frac{11h^4}{2688}n^{(k)5}\tilde{\Phi},\tag{15d}
$$

$$
\frac{-11}{12} \left[ \frac{Q_3^{(k)}}{c_{33}^{(k)}} + \frac{Q_3^{(k+1)}}{c_{33}^{(k+1)}} \right] + \frac{15}{2h} \left[ \frac{R_3^{(k)}}{n^{(k)}c_{33}^{(k)}} - \frac{R_3^{(k+1)}}{n^{(k+1)}c_{33}^{(k+1)}} \right]
$$
\n
$$
+ \frac{55}{3h^2} \left[ \frac{J_3^{(k)}}{n^{(k)}c_{33}^{(k)}} + \frac{J_3^{(k+1)}}{n^{(k+1)}c_{33}^{(k+1)}} \right] - \frac{70}{h^3} \left[ \frac{I_3^{(k)}}{n^{(k)}c_{33}^{(k)}} - \frac{I_3^{(k+1)}}{n^{(k+1)}c_{33}^{(k+1)}} \right]
$$
\n
$$
= \frac{h}{18} \left[ \frac{n^{(k)}}{c_{33}^{(k)}} T_3^{(k-1)} + 10 \left( \frac{n^{(k)}}{c_{33}^{(k)}} + \frac{n^{(k+1)}}{c_{33}^{(k+1)}} \right) T_3^{(k)} + \frac{n^{(k+1)}}{c_{33}^{(k+1)}} T_3^{(k+1)} \right]. \quad (15e)
$$

In eqns (14a–c) and (15a–d), k ranges from 1 to N, while in eqns (14d) and (15e), k ranges from 1 to  $(N-1)$ . Also, no summation on  $\alpha$  is implied in eqn (14) and

$$
\tilde{c}_a^{(k)} \equiv \delta_{a1} c_{55}^{(k)} + \delta_{a2} c_{44}^{(k)}, \quad n_0^{(k)} = \frac{x_{30}^{(k)}}{h} \tag{16}
$$

$$
\begin{bmatrix}\n\tilde{U} \\
\tilde{\Psi} \\
\tilde{S} \\
\tilde{\xi} \\
\tilde{\Phi}\n\end{bmatrix} = \begin{bmatrix}\nU_{1,1} & U_{2,2} \\
\Psi_{1,1} & \Psi_{2,2} \\
S_{1,1} & S_{2,2} \\
\xi_{1,1} & \xi_{2,2} \\
\Phi_{1,1} & \Phi_{2,2}\n\end{bmatrix} \begin{bmatrix}\nc_{13} \\
c_{23}\n\end{bmatrix}^{(k)}.
$$
\n(17)

By solving eqns (14) and (15),  $Q_i^{(k)}$ ,  $R_i^{(k)}$ ,  $J_i^{(k)}$ ,  $i_3^{(k)}$  and  $T_i^{(k)}$  are obtained in terms of  $U_i$ ,  $\Psi_i$ ,  $S_i$ ,  $\xi_i$  and  $\Phi_\alpha$  and their derivatives. As a result, the quantities  $N_{3i}$ ,  $M_{3i}$ ,  $K_{3i}$ ,  $Z_{3i}$ ,  $L_{3i}$  of eqn (13b) can be determined as functions of these displacement variables. Such expressions will automatically include the appropriate shear correction factors by virtue of the Reissner mixed variational principle.

The equilibrium equations (12) are supplemented with the following suitable boundary conditions:

specify 
$$
U_i
$$
 or  $N_{ai}v_{\alpha}$   
\nspecify  $\Psi_i$  or  $M_{ai}v_{\alpha}$   
\nspecify  $S_i$  or  $Z_{ai}v_{\alpha}$   
\nspecify  $\xi_i$  or  $L_{ai}v_{\alpha}$   
\nspecify  $\Phi_{\alpha}$  or  $P_{\beta\alpha}v_{\beta}$ . (18)

The remaining constitutive equations for  $N_{\alpha\beta}$ ,  $M_{\alpha\beta}$ ,  $Z_{\alpha\beta}$ ,  $L_{\alpha\beta}$  and  $P_{\alpha\beta}$  are obtained by substituting eqns (1a), (6) and (8b) into eqn (13a) to yield

$$
\begin{bmatrix}\n\frac{1}{h}\mathcal{N} \\
\frac{1}{h^2}\mathcal{M} \\
\frac{1}{h^2}\mathcal{Z} \\
\frac{1}{h^3}\mathcal{L} \\
\frac{1}{h^3}\mathcal{L}\n\end{bmatrix} = \begin{bmatrix}\n[N_U] & [N_{\Psi}] & 0 & [N_{\xi}] & [N_{\Phi}]\n\end{bmatrix}\n\begin{bmatrix}\nW_{\xi} & [N_{\Phi}] & [N_{\Phi}]\n\end{bmatrix}\n\begin{bmatrix}\nU \\
h_{\xi}^T \\
\frac{1}{2}[N_U] & [Z_{\xi}] & [Z_{\Phi}]\n\end{bmatrix}\n\begin{bmatrix}\nU \\
h_{\xi}^T \\
S \\
S \\
h_{\xi}^T\n\end{bmatrix}
$$
\nSymmetric\n
$$
\begin{bmatrix}\nL_{\xi}\n\end{bmatrix}\n\begin{bmatrix}\nL_{\xi}\n\end{bmatrix}\n\begin{bmatrix}\nL_{\phi}\n\end{bmatrix}\n\begin{bmatrix}\nU \\
h_{\xi}^T \\
S \\
h_{\xi}^T\n\end{bmatrix}
$$

$$
+ \sum_{i=1}^{N} [C]^{(k)} \begin{bmatrix} \underline{V}^{N} \\ \underline{V}^{M} \\ \underline{V}^{Z} \\ \underline{V}^{L} \\ \underline{V}^{L} \\ \underline{V}^{P} \end{bmatrix} \begin{bmatrix} Q_{3} \\ \frac{1}{h}R_{3} \\ \frac{1}{h^{2}}J_{3} \\ \frac{1}{h^{3}}I_{3} \end{bmatrix}^{(k)}
$$
(19)

where  $N = [N_{11}, N_{22}, N_{12}]^T$ ,  $U = [U_{1,1}, U_{2,2}, U_{1,2} + U_{2,1}]^T$  with same expressions for M<sub>1</sub>,  $\Psi \dots \underline{p}$ ,  $[\Phi, [N_U] \dots [P_{\Phi}]$  are  $3 \times 3$  matrices,  $[C]^{(k)}$  is a  $15 \times 5$  matrix and  $\overline{Y}^N \dots \overline{Y}^P$  are  $1 \times 4$ vectors.

#### 3. BENDING OF RECTANGULAR LAMINATED PLATES

The proposed theory can be used to solve the bending problem of rectangular plates for which two opposite edges are simply supported. The other two edges can each have arbitrary boundary conditions. Here we assume that the edges parallel to the  $x_2$ -axis are simply supported, and the origin of the coordinate system is taken as shown in Fig. 2. The simply supported boundary conditions can be satisfied by trigonometric functions in  $x_1$ . The resulting ordinary differential equations in  $x_2$  can be solved using the state-space concept.

The prescribed boundary conditions on the top and bottom surfaces of the plate are



Fig. 2. Geometry and coordinate system of rectangular plate.

2498 Liu Ping *et aI,*

$$
T_1^+ = T_2^+ = 0, \quad T_3^+ = q \quad \text{on } x_3 = \frac{h}{2} \tag{20a}
$$

$$
T_1^- = T_2^- = T_3^- = 0 \quad \text{on } x_3 = -\frac{h}{2}.\tag{20b}
$$

The following representations of the displacements and loading are assumed:

$$
\begin{bmatrix}\nU_1 \\
\Psi_1 \\
S_1 \\
\vdots \\
\Phi_1\n\end{bmatrix} = \sum_{m=1}^{\infty} \begin{bmatrix}\nh\hat{U}_{1m}(x_2) \\
h\hat{S}_{1m}(x_2) \\
\vdots \\
h\hat{S}_{1m}(x_2) \\
\vdots \\
h\hat{S}_{1m}(x_2)\n\end{bmatrix} \cos \alpha x_1 \begin{bmatrix}\nU_2 \\
\Psi_2 \\
S_2 \\
\vdots \\
S_2\n\end{bmatrix} = \sum_{m=1}^{\infty} \begin{bmatrix}\nh\hat{U}_{2m}(x_2) \\
h\hat{S}_{2m}(x_2) \\
\vdots \\
h\hat{S}_{2m}(x_2)\n\end{bmatrix} \sin \alpha x_1
$$
\n
$$
\begin{bmatrix}\nU_3 \\
\Psi_3 \\
S_3 \\
\vdots \\
S_4\n\end{bmatrix} = \sum_{m=1}^{\infty} \begin{bmatrix}\nh\hat{U}_{3m}(x_2) \\
\hat{\Psi}_{3m}(x_2) \\
\vdots \\
h\hat{S}_{3m}(x_2)\n\end{bmatrix} \sin \alpha x_1
$$
\n
$$
q = \sum_{m=1}^{\infty} Q_m(x_2) \sin \alpha x_1,
$$
\n(21)

where  $\alpha = m\pi/a$  and  $\hat{U}_{1m}$ .  $\hat{\xi}_{3m}$  and  $Q_m$  denote amplitudes of  $U_1 \dots \xi_3$  and  $q$ , respectively. It is easily proven that eqn (21) can satisfy boundary condition of simply supported on  $x_1 = 0$ , *a* i.e. at  $x_1 = 0$ , *a* 

$$
U_3 = \Psi_3 = S_3 = \xi_3 = 0 \quad \text{and} \quad N_{11} = M_{11} = Z_{11} = L_{11} = P_{11} = 0. \tag{23}
$$

Then inserting eqn (21) into constitutive equations and these with eqn (22) in turn into the equilibrium eqn (12), yields a system of fourteen ordinary differential equations in the  $x_2$ coordinate, which can be reduced to a single matrix differential equation using the statespace concept (Franklin, 1986)

$$
X' = AX + B. \tag{24}
$$

This can be done by introducing the variables

$$
X=[\hat{U}_{1m}\hat{U}_{1m}\hat{\Psi}_{1m}\hat{\Psi}_{1m}\hat{S}_{1m}\hat{S}_{1m}\hat{\xi}_{1m}\hat{\xi}_{1m}\hat{\Phi}_{1m}\hat{\Phi}_{1m}\hat{U}_{2m}\hat{U}_{2m}\ldots\hat{\Phi}_{2m}\hat{\Phi}_{2m}\hat{U}_{3m}\hat{U}_{3m}\ldots\hat{\xi}_{3m}\hat{\xi}_{3m}]^{T},
$$

where A is a  $28 \times 28$  matrix which depends on the volume fractions  $n^{(k)}$  and elastic constants  $\bar{c}_{ij}$  and *B* is a  $1 \times 28$  vector which depends on  $Q_m$ .

The solution of eqn (24) is given by

$$
X = e^{Ax_2}K + e^{Ax_2} \int_{-b/2}^{x_2} e^{-A\eta} B d\eta,
$$
 (25)

where K is a  $1 \times 28$  constant vector to be determined from the boundary conditions, while  $e^{Ax_2}$  is defined by

$$
e^{Ax_2} = [L] \begin{bmatrix} e^{\lambda_1 x_2} & 0 \\ e^{\lambda_2 x_2} & 0 \\ \cdot & \cdot \\ 0 & e^{\lambda_2 s x_2} \end{bmatrix} [L]^{-1}, \qquad (26)
$$

where [L] is the matrix of eigenvectors,  $\lambda_i$  ( $i = 1, 2...28$ ) denote the distinct eigenvalues associated with the matrix A and  $[L]^{-1}$  is the inverse of the matrix  $[L]$ .

The following boundary conditions are used on the remaining two edges (i.e. the edges parallel to the  $x_1$ -axis) at  $x_2 = \pm b/2$ :

simply supported

$$
U_1 = \Psi_1 = S_1 = \xi_1 = \Phi_1 = 0
$$
  
\n
$$
U_3 = \Psi_3 = S_3 = \xi_3 = 0
$$
  
\n
$$
N_{22} = M_{22} = Z_{22} = L_{22} = P_{22} = 0;
$$
\n(27a)

clamped

$$
U_1 = \Psi_1 = S_1 = \xi_1 = \Phi_1 = 0
$$
  
\n
$$
U_2 = \Psi_2 = S_2 = \xi_2 = \Phi_2 = 0
$$
  
\n
$$
U_3 = \Psi_3 = S_3 = \xi_3 = 0;
$$
\n(27b)

free

$$
N_{12} = N_{22} = N_{23} = 0
$$
  
\n
$$
M_{12} = M_{22} = M_{23} = 0
$$
  
\n
$$
Z_{12} = Z_{22} = Z_{23} = 0
$$
  
\n
$$
L_{12} = L_{22} = L_{23} = 0
$$
  
\n
$$
P_{12} = P_{22} = 0.
$$
\n(27c)

## 4. NUMERICAL RESULTS AND DISCUSSION

The following numerical examples are presented: (a) Numerical results are presented for orthotropic and symmetric cross-ply  $(0^{\circ}/90^{\circ}/0^{\circ})$ plate with same thickness layer subject to three types of loads; uniformly distributed load  $(q_0)$ , triangular distributed load  $(2q_0)$  and concentrated load p, as shown in Fig. 3.

The following dimensionless orthotropic material properties are used:

$$
\frac{E_1}{E_0} = 20.83
$$
\n
$$
\frac{E_2}{E_0} = 10.94
$$
\n
$$
E_3 = E_2
$$
\n
$$
\frac{G_{12}}{E_0} = 6.10
$$
\n
$$
\frac{G_{13}}{E_0} = 3.71
$$
\n
$$
\frac{G_{23}}{E_0} = 6.19
$$
\n
$$
v_{12} = v_{13} = v_{23} = 0.44
$$
\n
$$
E_0 = 1 \times 10^6 \text{ psi.}
$$



Fig. 3. Various types of transverse loads.

All results are compared with Khdeir's solution (Khdeir *et al.,* 1987) as shown in Tables 1-3. Tables 1-2 contain center deflections  $\bar{u}_3$  for orthotropic and symmetric crossply (0°/90°/0°) plates, while Table 3 contains non-dimensionalized axial stresses  $\sigma_{11}$  for cross-ply (0°/90°/0°) plate.

The following notation has been used throughout the tables:

- SS simply supported at  $x_2 = -b/2$  and at  $x_2 = b/2$ ;<br>CC clamped at  $x_2 = -b/2$  and at  $x_2 = b/2$ ;
- CC clamped at  $x_2 = -b/2$  and at  $x_2 = b/2$ ;<br>FF free at  $x_2 = -b/2$  and at  $x_2 = b/2$ ;
- free at  $x_2 = -b/2$  and at  $x_2 = b/2$ ;
- SC simply supported at  $x_2 = -b/2$  and clamped at  $x_2 = b/2$ ;
- SF simply supported at  $x_2 = -b/2$  and free at  $x_2 = b/2$ ;
- CF clamped at  $x_2 = -b/2$  and free at  $x_2 = b/2$ ;
- UN uniformly distributed load;
- TR triangular distributed load;
- PL point load at the center of the plate.

Figure 4 shows the thickness variations of axial stresses  $\bar{\sigma}_{11}$  of  $(0^{\circ}/90^{\circ}/0^{\circ})$  laminated plate for various boundary conditions.

(b) Center deflections and stresses for cross-ply plates under sinusoidal transverse loading

$$
\left(\text{i.e. } q = q_0 \sin \frac{\pi}{a} x_1 \cos \frac{\pi}{b} x_2\right)
$$

are calculated. The plates are simply supported at four edges. The numerical results are compared with exact elastic solution obtained by Pagano (1970).

The following material properties are used:

$$
\frac{E_1}{E_0} = 25 \qquad \frac{E_2}{E_0} = 1.0 \qquad E_3 = E_2
$$

$$
\frac{G_{12}}{E_0} = 0.5 \qquad G_{13} = G_{12} \qquad \frac{G_{23}}{E_0} = 0.2
$$

$$
v_{12} = v_{13} = v_{23} = 0.25 \qquad E_0 = 1 \times 10^6 \text{ psi.}
$$

We follow Pagano's non-dimensionalization and write the center deflection and stresses in the form:

$$
\bar{u}_3 = \frac{100E_0h^3}{q_0a^4} u_3\left(\frac{a}{2}, 0, 0\right)
$$
\n
$$
\bar{\sigma}_{11} = \frac{h^2}{q_0a^2} \sigma_{11}\left(\frac{a}{2}, 0, x_3\right), \qquad \bar{\sigma}_{22} = \frac{h^2}{q_0a^2} \sigma_{22}\left(\frac{a}{2}, 0, x_3\right)
$$
\n
$$
\bar{\tau}_{12} = \frac{h^2}{q_0a^2} \tau_{12}\left(0, -\frac{b}{2}, x_3\right), \quad \bar{\tau}_{23} = \frac{h}{q_0a} \tau_{23}\left(\frac{a}{2}, -\frac{b}{2}, x_3\right)
$$
\n
$$
\bar{\tau}_{31} = \frac{h}{q_0a} \tau_{31}(0, 0, x_3), \qquad \bar{\sigma}_{33} = \frac{h}{q_0a} \sigma_{33}\left(\frac{a}{2}, 0, x_3\right).
$$

Also

$$
\bar{x}_1 = x_1/h \quad S = a/h.
$$

Tables 4-6 show the center deflections and in-plane stresses and transverse shear stresses of the various side-to-thickness ratios for cross-ply rectangular plate  $(0^{\circ}/90^{\circ}/0^{\circ}$ ,

				<b>SS</b>	CC			FF		<b>SC</b>	<b>SF</b>		CF	
a/b	h/a	Loading	Khdeir's solution	Present solution	Khdeir's solution	Present solution	Khdeir's solution	Present solution	Khdeir's solution	Present solution	Khdeir's solution	Present solution	Khdeir's solution	Present solution
3	0.2	<b>UN</b> TR <b>PL</b>	6.29 9.60 20.95	5.632 8.537 18.564	3.19 5.29 14.46	3.183 5.198 13.131	224.4 289.2 371.4	221.015 284.581 363.787	4.38 6.98 17.09	4.137 6.509 15.071	50.14 66.30 93.46	49.025 64.607 89.541	17.055 24.49 40.99	17.064 23.688 38.443
	0.14	<b>UN</b> TR PL	14.23 21.15 42.38	13.512 19.874 39.931	5.89 9.71 25.71	5.881 9.592 24.277	593.1 761.9 966.8	590.463 756.991 958.142	8.74 13.71 31.83	8.498 13.017 29.976	124.72 163.50 222.8	121.714 160.533 199.124	40.13 55.13 87.19	39.771 53.976 84.818
4	0.2	UN TR PL	2.72 4.47 12.38	2.293 3.738 10.033	1.53 2.68 9.10	1.529 2.635 8.002	226.3 291.6 374.6	222.999 287.178 367.125	2.03 3.44 10.53	1.871 3.121 8.834	34.64 46.13 67.12	33.915 44.991 63.957	8.07 11.91 23.69	7.873 11.534 21.839
	0.14	UN TR PL	5.70 9.14 23.36	5.211 8.227 21.003	2.66 4.66 15.59	2.657 4.432 14.417	599.1 769.6 976.6	596.741 764.697 967.934	3.76 6.32 18.66	3.591 5.827 17.144	83.60 110.34 154.51	81.914 108.612 151.751	17.53 25.36 47.13	17.079 24.302 45.291
	0.2	<b>UN</b> TR PL	1.46 2.52 8.39	1.148 1.959 6.204	0.88 1.59 6.32	0.883 1.552 5.327	227.1 292.8 376.1	223.913 288.391 368.745	1.14 2.01 7.27	1.014 1.748 5.721	25.97 34.76 51.86	25.465 33.936 49.151	4.29 6.71 15.77	4.213 6.512 14.267
5	0.14	<b>UN</b> TR <b>PL</b>	2.85 4.84 15.15	2.494 4.014 13.455	1.49 2.70 10.69	1.492 2.613 9.884	601.8 773.2 981.3	598.976 767.899 972.176	2.03 3.56 12.57	1.911 3.071 11.224	60.68 80.51 115.45	58.196 78.877 113.006	8.87 13.58 29.86	8.403 12.978 28.035

Table 1. Center deflections  $\bar{u}_3$  of orthotropic plates

 $\bar{u}_3 = [u_3(a/2, 0, 0)/q_0]E_0, \quad a = 200$ in.

			<b>SS</b>		CC			FF		<b>SC</b>		<b>SF</b>		CF
a/b	h/a	Loading	Khdeir's solution	Present solution										
		UN	6.85	6.376	3.86	3.861	215.9	214.727	5.10	4.905	47.67	47.296	18.86	18.591
	0.2	TR	10.23	9.491	6.18	6.123	277.7	276.120	7.87	7.532	62.82	62.211	25.97	25.529
		PL.	20.61	18.460	14.92	13.83	354.5	351.160	17.34	15.813	87.27	85.245	47.32	43.621
3		UN	14.88	14.421	6.90	6.897	585.5	585.5	9.81	9.674	121.06	120.502	41.87	41.227
	0.14	TR	21.80	20.960	11.08	11.026	751.3	748.052	15.05	14.782	158.35	157.397	57.09	56.079
		<b>PL</b>	41.18	39.867	26.33	25.818	949.4	944.936	31.99	31.053	213.4	211.454	87.32	85.433
		UN	3.12	2.811	1.87	1.872	217.8	216.723	2.43	2.274	32.34	32.198	9.03	8.902
	0.2	TR	4.99	4.409	3.19	3.135	280.2	278.713	4.00	3.709	42.98	42.663	13.06	12.813
		PL.	12.47	10.871	9.48	8.485	357.6	354.452	10.85	9.375	61.72	60.065	24.09	22.678
4		UN	6.23	5.927	3.21	3.181	591.4	589.061	4.38	4.212	80.07	79.785	18.88	18.544
	0.14	TR	9.78	9.159	5.47	5.431	758.9	755.841	7.18	6.912	105.47	105.008	26.99	26.453
		PL	23.01	20.813	16.16	15.832	959.1	945.404	19.00	18.368	146.04	144.705	47.58	46.573
		UN	1.73	1.545	1.08	1.074	218.7	217.661	1.38	1.245	23.78	23.761	4.95	4.887
	0.2	TR	2.91	2.514	1.90	1.852	281.3	279.948	2.37	2.112	31.80	31.666	7.53	7.385
		PL	8.64	7.109	6.65	5.962	359.1	356.743	7.59	6.949	46.90	45.544	16.11	14.862
5		<b>UN</b>	3.23	2.963	1.82	1.802	594.2	591.939	2.41	2.316	57.29	57.232	9.84	9.682
		TR	5.36	4.859	3.21	3.196	762.6	759.587	4.13	3.915	75.91	75.726	14.81	14.527
		PL	15.19	13.964	11.21	11.014	963.8	959.284	12.97	12.415	107.72	106.813	30.33	29.535

Table 2. Center deflections  $\bar{u}_3$  of cross-ply  $0^{\circ}/90^{\circ}/0^{\circ}$  laminates

 $\tilde{u}_3 = [u_3(a/2, 0, 0)/q_0]E_0$ ,  $a = 200$ in.

			SS		cc		FF		<b>SC</b>		<b>SF</b>		CF	
a/b	h/a	Loading	Khdeir's solution	Present solution	Khdeir's solution	Present solution	Khdeir's solution	Present solution	Khdeir's solution	Present solution	Khdeir's solution	Present solution	Khdeir's solution	Present solution
	0.2	UN TR PL	1.082 2.115 11.160	0.973 1.808 10.911	0.482 1.262 9.792	0.480 1.134 9.735	19.66 26.51 43.66	19.082 25.554 42.344	0.729 1.619 10.386	0.691 1.426 10.036	4.272 6.513 17.708	4.064 6.064 17.112	1.098 2.402 12.419	1.020 2.148 12.143
3	0.14	UN TR <b>PL</b>	2.106 3.983 17.928	1.982 3.623 17.001	0.794 2.077 14.814	0.729 1.934 14.211	39.54 53.01 82.76	38.911 51.648 80.043	1.262 2.784 16.049	1.209 2.479 15.133	8.519 12.766 30.78	8.003 11.879 28.333	1.622 3.799 19.17	1.541 3.481 18.327
	0.2	<b>UN</b> TR PL	0.620 1.305 9.072	0.582 1.123 8.912	0.289 0.802 8.082	0.274 0.739 7.974	19.67 26.52 43.74	19.091 25.569 42.827	0.439 1.032 8.546	0.425 0.912 8.213	2.602 4.213 14.181	2.432 3.843 13.792	0.263 1.138 10.054	0.238 0.982 9.862
4	0.14	UN TR PL.	1.156 2.350 13.949	1.092 2.119 13.231	0.455 1.260 11.835	0.423 1.147 11.521	39.62 53.13 83.03	38.925 51.992 80.565	0.725 1.695 12.735	0.681 1.544 12.136	5.278 8.319 24.05	5.081 8.077 23.588	0.185 1.586 14.967	0.385 1.478 14.001
	0.2	UN TR PL.	0.427 0.927 7.725	0.404 0.803 7.589	0.215 0.588 6.890	0.211 0.533 6.571	19.66 26.51 43.75	19.098 25.573 43.142	0.321 0.756 7.298	0.315 0.697 6.943	1.673 2.879 11.859	1.519 2.552 11.512	0.027 0.662 8.680	0.024 0.612 8.328
5	0.14	UN TR PL	0.759 1.593 11.476	0.720 1.369 11.029	0.321 0.883 9.863	0.306 0.791 9.583	39.63 53.16 83.14	38.952 52.024 80.889	0.507 1.190 10.592	0.481 1.067 10.029	3.492 5.773 19.74	3.315 5.485 18.502	$-0.175$ 0.808 12.645	0.047 0.723 11.938

Table 3. Axial center stresses  $\bar{\sigma}_{11}$  of cross-ply 0°/90°/0° laminates

 $\sigma_{11} = \sigma_{11}(a/2, 0, h/2)/q_0E_0$ ,  $a = 200$ in.









*0.50*











Fig. 4. Thickness variations of  $\sigma_{11}$  for various boundary conditions  $(a/b = 3, a/h = 5, UN)$ :<br>(a) - SSSS; (b) - SSCC; (c) - SSFF; (d) - SSSC; (e) - SSSF; (f) - SSCF.

 $b/a = 3$ ) and square plates  $[0^{\circ}/90^{\circ}/90^{\circ}/0^{\circ}$ ,  $0^{\circ}/90^{\circ} \dots 0^{\circ}$  (9 layers)] with the same thickness layer, respectively.

For the side-to-thickness ratio  $S = 0$ , the thickness variations of in-plane and transverse shear and normal stresses for  $0^{\circ}/90^{\circ}/0^{\circ}$  laminated plate are shown in Fig.  $\overline{S}$ 







From Tables 1-3, it is shown that the center deflections and stresses are slightly smaller than those obtained by Khdeir. This is because the present theory includes the effect of transverse normal strain  $(\varepsilon_{33})$  and stress  $(\sigma_{33})$ . While this theory can satisfy the continuity condition of transverse shear stresses at the interfaces, this is not true for Khdeir's theory.

From Tables 4–6, close agreement for the center deflections and stresses of the present theory and the exact solution obtained by Pagano are observed for different side-tothickness ratio and lamination schemes, which proves that the displacement field and trial transverse and normal stresses field of the present theory are appropriate and reasonable.

In the present work, transverse shear stresses  $\tau_{31}$  and  $\tau_{32}$  and transverse normal stress  $\tau_{33}$  are obtained from eqn (8), which satisfy the top and bottom surfaces boundary

$\boldsymbol{S}$	Theory	$\bar{u}_3$	$\sigma_{11}\left(\frac{h}{2}\right)$	$\frac{h}{4}$ $\sigma_{22}$	$\sigma_{23}(0)$	$\hat{\sigma}_{31}(0)$	$\bar{\sigma}_{12}$
	Pagano's solution	1.954	0.720	0.663	0.292	0.291	$-0.0467$
$\overline{\mathbf{4}}$	Present solution	1.884	0.7364	0.5908	0.2343	0.2285	$-0.04612$
	Pagano's solution	0.743	0.559	0.401	0.196	0.301	$-0.0275$
10	Present solution	0.7097	0.5499	0.3813	0.1548	0.3085	$-0.02678$
	Pagano's solution	0.517	0.543	0.308	0.156	0.328	$-0.0230$
10	Present solution	0.4980	0.5315	0.2984	0.1245	0.3340	$-0.02246$
	Pagano's solution	0.4385	0.539	0.276	0.141	0.337	$-0.0216$
100	Present solution	0.4247	0.5267	0.2648	0.1123	0.3440	$-0.02087$

Table 5. Center deflections and stresses of 0°/90°/90°/0° laminates



conditions prescribed by eqn (20) (also see Fig. 5). Reddy (1984a) pointed out that the alternate procedure of computing the transverse stresses by integrating the equilibrium equations using the in-plane stresses found directly from the displacement solution yields more accurate results.

The first-order zig-zag theory proposed by Murakami (1986) is a particular case of this present theory. The author has applied it to the bending problem of rectangular plates. For  $0^{\circ}/90^{\circ}/0^{\circ}$  plate, better results were obtained, but for  $0^{\circ}/90^{\circ}/0^{\circ}/90^{\circ}$  and  $0^{\circ}/90^{\circ}/90^{\circ}/0^{\circ}$ plates, the first-order zig-zag theory deviates significantly from the exact solution. However, the present theory is still very good when compared with the exact solution. Obviously, the

Bending solution of high-order refined shear deformation theory 2507

S	Theory	$\bar{u}_3$	$^{\prime}$ h $^{\prime}$ $\sigma_{11}$ $\overline{2}$	2h $\sigma_{22}$ $\overline{5}$	$\sigma_{23}(0)$	$\sigma_{31}(0)$	'h` $\overline{2}$ $\sigma_{12}$
	Pagano's solution	1.7590	0.684		0.203	0.223	$-0.0337$
4	Present solution	1.7501	0.6620	0.02946	0.1990	0.2458	$-0.03333$
	Pagano's solution	0.6520	0.551		0.226	0.247	$-0.0233$
10	Present solution	0.6409	0.5341	0.02286	0.1878	0.2773	$-0.02296$

Table 6. Center deflections and stresses of  $0^{\circ}/90^{\circ}$ ... $0^{\circ}$  (9 layers) laminates

present theory is suitable for arbitrary laminated configurations, so it is the development of the first-order zig-zag theory.

#### 5. CONCLUSION

An improved high-order shear deformation theory based upon Reissner's mixed variational principle in conjunction with the state-space concept is developed to determine the bending problems for rectangular laminated composite plate. Numerical results are presented for different edge conditions, aspect ratios, lamination schemes and loadings and are compared with Khdeir and Pagano's theories. The comparison indicates that the present theory accurately estimates in-plane responses, even for small side-to-thickness ratios and large layer laminates.

*Acknowledgement-The* support of the Natural Science Foundation of China is gratefully acknowledged.

#### REFERENCES

Bert, C. W. and Chen, T. L. C. (1978). Effect of shear deformation on vibration of antisymmetric angle-ply laminated rectangular plates. *Int.* J. *Solids Structures* 14,465-473.

Franklin, J. N. (1986). *Matrix Theory.* Prentice-Hall, Englewood Cliffs, New Jersey.

Hussainy, S. A. and Srinivas, S. (1975). Flexure of rectangular composite plates. *Fibre Sci. Technol.* 8, 59-76.

Khdeir, A. A., Reddy, J. N. and Librescu, L. (1987). Analytical solution of a refined shear deformation theory for rectangular composite plates. *Int.* J. *Solids Structures* 23, 1447-1463.

- Murakami, H. (1986). A laminated composite plate theory with improved in-plane responses. *ASME* J. *Appl. Mech.* 53,661-666.
- Pagano, N. J. (1970). Exact solutions for rectangular bidirectional composites and sandwich plates. J. *Composite Mater.* 4, 20-34.
- Reddy, J. N. (l984a). A simple higher-order theory for laminated plates. J. *Appl. Mech.* 51, 745-752.
- Reddy, J. N. (I 984b). A refined nonlinear theory of plates with transverse shear deformation. *Int.* J. *Solids Structures* 20,881-896.

Reddy, J. N. and Chao, C. W. (1981). A comparison of closed form and finite element solutions ofthick laminated anisotropic rectangular plates. *Nucl. Engng Des.* 64, 153-167.

Reddy, J. N. and Phan, N. D. (1985). Stability and vibration of isotropic, orthotropic and laminated plates according to a higher-order shear deformation theory. J. *Sound Vibr.* 98(2), 157-170.

Reddy, J. N., Khdeir, A. A. and Librescu, L. (1987). The Levy type solutions for symmetric rectangular composite plates using the first-order shear deformation theory. J. *Appl. Mech.* 54, 740-742.

Reissner, E. (1984). On a certain mixed variational theorem and a proposed application. *Int. J. Num. Mech. Engng* 20, 1366-1368.

Srinivas, S. and Rao, A. K. (1970). Bending, vibration and buckling of simply supported thick orthotropic rectangular plates and laminates. *Int.* J. *Solids Structures* 6,1463-1481.

Srinivas, S., Joga, C. V. and Rao, A. K. (1970). An exact analysis for vibration of simply supported homogeneous and laminated thick rectangular plates. J. *Sound Vibr.* 12, 187-199.

Whitney, J. M. and Leissa, A. W. (1969). Analysis of heterogeneous anisotropic plates. J. *Appl. Mech.* 36, 261- 266.

Whitney, J. M. and Pagano, N. J. (1970). Shear deformation in heterogeneous anisotropic plates. J. *Appl. Mech.* 37,1031-1036.